**import RPi.GPIO as GPIO**

**from time import sleep**

**GPIO.setmode(GPIO.BCM)**

**Motor1A = 02**

**Motor1B = 03**

**Motor1E = 04**

**GPIO.setup(Motor1A,GPIO.OUT)**

**GPIO.setup(Motor1B,GPIO.OUT)**

**GPIO.setup(Motor1E,GPIO.OUT)**

**print "Motor going to Start"**

**GPIO.output(Motor1A,GPIO.HIGH) # to run motor in clockwise direction**

**GPIO.output(Motor1B,GPIO.LOW) # put it high to rotate motor in anti-clockwise direction**

**GPIO.output(Motor1E,GPIO.HIGH) # Should be always high to start motor**

**sleep(5)**

**print "Stopping motor"**

**GPIO.output(Motor1E,GPIO.LOW) # to stop the motor**

**GPIO.cleanup()**